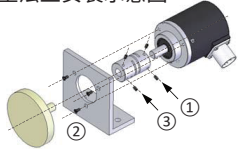


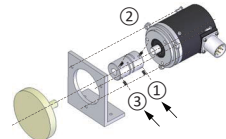
轴型编码器安装:

A型/C型法兰安装示意图



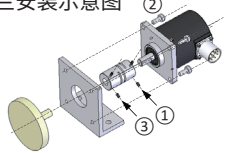
- ① 将联轴器安装到编码器
- ② 将编码器安装到支架
- ③ 将联轴器套装于被测轴上

B型法兰安装示意图



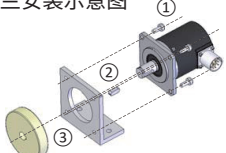
- ① 将联轴器安装到编码器
- ② 将编码器通过偏心器安装到支架上
- ③ 将联轴器套装于被测轴上

D型法兰安装示意图



- ① 将联轴器安装到编码器
- ② 将编码器安装到支架上
- ③ 将联轴器套装于被测轴上

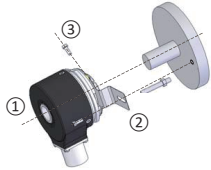
M型法兰安装示意图



- ① 将编码器安装到支架上
- ② 将键装入键槽
- ③ 将编码器安装到电机上

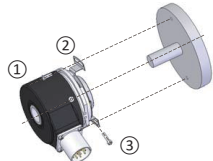
轴套型编码器安装:

单翼弹簧片安装示意图



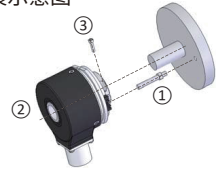
- ① 将编码器套装于电机上
 - ② 固定弹簧片
 - ③ 紧固编码器锁圈螺丝
- 注:产品安装要以弹簧片本身不发生任何形变为标准

双翼弹簧片安装示意图



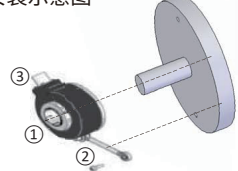
- ① 将编码器套装于电机上
 - ② 固定弹簧片
 - ③ 紧固编码器锁圈螺丝
- 注:产品安装要以弹簧片本身不发生任何形变为标准

挡销安装示意图



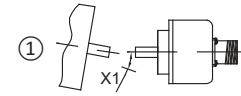
- ① 将挡销安装于电机或者支架上
- ② 将编码器通过挡销套装于被测轴上,确保挡销尾端面与支撑槽底有0.8 mm的余量
- ③ 紧固编码器锁圈螺丝

拐臂安装示意图

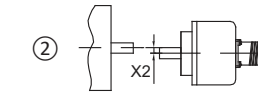


- ① 将编码器套装于被测轴上
 - ② 固定方向扭矩臂
 - ③ 紧固编码器锁圈螺丝
- 注:产品正确安装时拐臂不能与编码器外壳接触

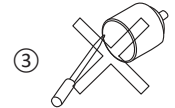
安装注意事项:



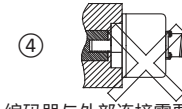
编码器与被测物体轴之间的角度偏差 $X1 < 1.5^\circ$ 。



编码器与驱动输出轴之间的径向偏差 $X2 < 0.1 \text{ mm}$ 。



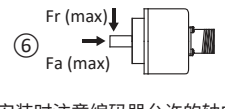
禁止局部或部分拆卸或改装编码器。



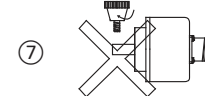
编码器与外部连接需要避免刚性连接。



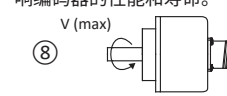
编码器是高精度仪器,安装时严禁敲击和磕碰,安装或使用不当会影响编码器的性能和寿命。



安装时注意编码器允许的轴向/径向最大负载,严禁超过最大值。



禁止对编码器轴进行打磨、切割、钻孔等任何加工处理。



注意不要超过编码器的极限转速,否则可能出现信号丢失。

电气参数:

接口协议	Profibus-DP
供电电压	10 ... 30 V DC

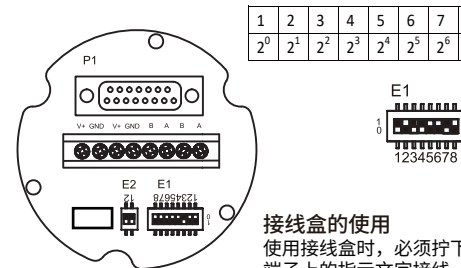
端子配置:

V+	电源供电	1
GND	供电地 0V	3
B (IN)	Profibus-DP入线 (红)	4
A (IN)	Profibus-DP入线 (绿)	2
B (OUT)	Profibus-DP出线 (红)	4
A (OUT)	Profibus-DP出线 (绿)	2

端子配置-M12接插件:



总线入端子 Bus in 电源端子 总线出端子 Bus out



E1:地址设定用
DIP1-DIP7:编码器地址设定开关,采用二进制运算,示数默认地址为4
DIP8: CW(顺时针)与CCW(逆时针)方向改变按钮,即计数方向改变。
E2:终端触点 DIP1-DIP2默认为ON,同时为ON,终端阻值为220 Ω,仅用于终端编码器设置,其余位置设置均为OFF。
例:图示为DIP1-DIP7,1011001=77,同时DIP8为ON,计数方向改变

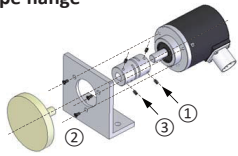
接线盒的使用

使用接线盒时,必须拧下后部端盖上的四个螺丝,将后部端盖从编码器主体上移走。根据接线端子上的指示文字接线。

注意:要在Profibus-DP主站中设置参数和配置从站,必须使用编码器相应的gsd设备文件。

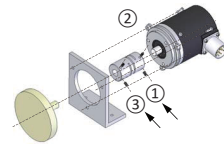
ENCODER INSTALLATION

A/C type flange



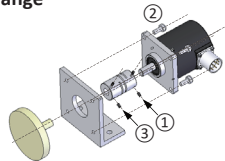
- ① Install coupling onto the encoder
- ② Install encoder onto the stand
- ③ Install the coupling onto the motor shaft

B type flange



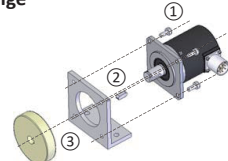
- ① Install coupling onto the encoder
- ② Install encoder onto the stand via eccentricizer
- ③ Install the coupling onto the motor shaft

D type flange



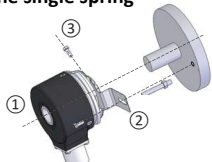
- ① Install coupling onto the encoder
- ② Install encoder onto the stand
- ③ Install the coupling onto the motor shaft

M type flange



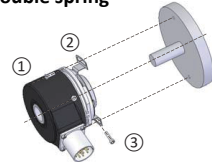
- ① Install encoder onto the stand
- ② Install the key into the keyslot
- ③ Install encoder onto the motor

Standard hollow shaft encoders equipped with the single spring



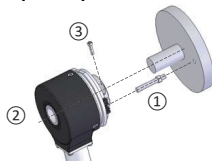
- ① Install the encoder on the motor
- ② Fasten the spring
- ③ Tighten the screws on encoder

Standard hollow shaft encoders equipped with the double spring



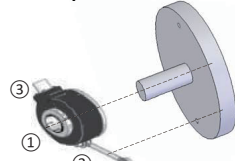
- ① Install the encoder on the motor
- ② Fasten the spring
- ③ Tighten the screws on encoder

Standard hollow shaft encoders equipped with torque stop



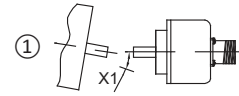
- ① Install the torque stop on the motor or bracket
- ② Install the encoder on the measured shaft via torque stop. Make sure there is 0.8 mm gap between the end side of the torque and the support trench
- ③ Tighten the screws on encoder

Standard hollow shaft encoders equipped with universal torque arm

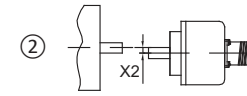


- ① Install the encoder on the motor
- ② Fasten the universal torque arm
- ③ Tighten the screws on encoder

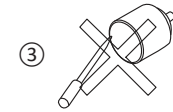
INSTALLATION ATTENTION



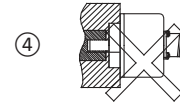
The angle deviation between the encoder and shaft is $X1 < 1.5^\circ$.



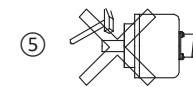
The radial deviation between the encoder and shaft is $X2 < 0.1 \text{ mm}$.



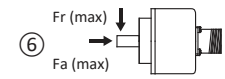
No modification.



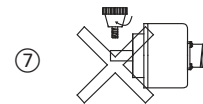
Don't use rigid connection between encoder and flange.



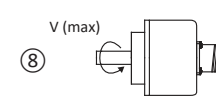
No hammer and impact.



Axial and radial load not beyond the limit.



No machining to the shaft. (Inc. skiving, sawing, drilling)



Not beyond $V(\text{max})$, otherwise signal will be lost.

ELECTRICAL PARAMETERS

Protocol type	Profibus-DP
Supply voltage	10 ... 30 V DC

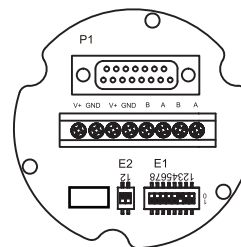
TERMINAL ASSIGNMENT

V+	Supply voltage	1
GND	Grounding	3
B (IN)	Profibus-DP input (RED)	4
A (IN)	Profibus-DP input (GREEN)	2
B (OUT)	Profibus-DP output (RED)	4
A (OUT)	Profibus-DP output (GREEN)	2

TERMINAL ASSIGNMENT- M12 Connector



Bus input Power Bus output



Terminal interface

1	2	3	4	5	6	7	8
2 ⁰	2 ¹	2 ²	2 ³	2 ⁴	2 ⁵	2 ⁶	-



E1: Address DIP switch
 DIP1-DIP7: Address setting is binary code, the default address is 4 in the diagram.
 DIP8: CW/CCW button, the counting direction can be changed.
 E2: DIP1-DIP2 terminal setting is default 'ON' when the terminal is encoder, and terminal resistance is 220 Ω, otherwise please turn switch 'OFF'.
 e.g. DIP1-DIP7, 1011001=77, DIP8 ON

Open the rear cover of the encoder and connect the wire according to the instructions on the terminal.

Note: To set parameters and configure the slave in the Profibus-DP master, it is necessary to use the appropriate gsd file of encoder.